

# STATEMENT OF COMPLIANCE

Statement No:  
**001/190227**  
DNV GL Id No:  
**10053962**

## Particulars of Product

Function Area: Bridge Operation Simulator  
Class notation: INTEGRATED SIMULATOR SYSTEM, TUG, HSC, DP,IN  
Name and type designation: Nautis Ship Simulator Bridge operations, Nautis 3

## Particulars of Manufacturer

Manufacturer: VSTEP B.V.  
Manufacturer address: Weena 690, 23rd floor, 3012 CN Rotterdam, The Netherlands

## This is to confirm:

That the above product is found to comply with Class A- Standard for Certification of Maritime Simulators No. DNVGL-ST-0033 April 2018.

## Application

The above Standard is based on requirements in the STCW Convention, Regulation I/12 and corresponding industry standard and guidelines.

This Statement is valid until **2024-02-27**, provided the requirements for the retention of the Statement will be complied with.

Issued at **Sandefjord** on **2019-02-27**



**Capt. Aksel David Nordholm**  
Manager Simulator Certification

for **DNV GL**




**Paul Kuin**  
Auditor



## Application/Limitation

The simulator is capable of simulating a realistic environment for all of the applicable STCW competence requirements referred to in the column for Class A, B, C and S in Table 3-2.

| <b>Table 3-2 Competencies addressed by bridge operation simulator class</b> |   |                      |                      |                      |                      |
|---|---|----------------------|----------------------|----------------------|----------------------|
| <i>STCW reference</i>   | <i>Competence</i>   | <i>Class A (NAV)</i> | <i>Class B (NAV)</i> | <i>Class C (NAV)</i> | <i>Class S (NAV)</i> |
| Table A-II/1.1  | Plan and conduct a passage and determine position   | A                    | B                    |                      | (S)                  |
| Table A-II/1.2  | Maintain a safe navigational watch  | A                    | B                    |                      | (S)                  |
| Table A-II/1.3  | Use of radar and ARPA to maintain safety of navigation  | A                    | B                    | C                    | (S)                  |
| Table A-II/1.4  | Use of ECDIS to maintain the safety of navigation   | A                    | B                    | C                    | (S)                  |
| Table A-II/1.5  | Respond to emergencies  | A                    | B                    | C                    | (S)                  |
| Table A-II/1.6  | Respond to a distress signal at sea   | A                    | B                    | C                    | (S)                  |
| Table A-II/1.8  | Transmit and receive information by visual signalling   | A                    | B                    | C                    | (S)                  |
| Table A-II/1.9  | Manoeuvre the ship  | A                    | B                    | C                    | (S)                  |
| Table A-II/2.1  | Plan a voyage and conduct navigation  | A                    | B                    |                      | (S)                  |
| Table A-II/2.2  | Determine position and the accuracy of resultant position fix by any means  | A                    | B                    |                      | (S)                  |
| Table A-II/2.3  | Determine and allow for compass errors  | A                    | B                    |                      | (S)                  |
| Table A-II/2.4  | Co-ordinate search and rescue operations  | A                    | B                    |                      | (S)                  |
| Table A-II/2.5  | Establish watchkeeping arrangements and procedures  | A                    | B                    |                      | (S)                  |
| Table A-II/2.6  | Maintain safe navigation through the use of information from navigation equipment and systems to assist command decision-making | A                    | B                    | C                    | (S)                  |
| Table A-II/2.7  | Maintain the safety of navigation through the use of ECDIS and associated navigation systems to assist command decision making  | A                    | B                    | C                    | (S)                  |
| Table A-II/2.10   | Manoeuvre and handle a ship in all conditions   | A                    |                      |                      | (S)                  |
| Table A-II/2.11   | Operate remote controls of propulsion plant and engineering systems and services  | A                    |                      |                      | (S)                  |
| Table A-II/3.1  | Plan and conduct a coastal passage and determine position   | A                    | B                    |                      | (S)                  |
| Table A-II/3.2  | Maintain a safe navigational watch  | A                    | B                    |                      | (S)                  |
| Table A-II/3.3  | Respond to emergencies  | A                    | B                    | C                    | (S)                  |
| Table A-II/3.4  | Respond to a distress signal at sea   | A                    | B                    | C                    | (S)                  |
| Table A-II/3.5  | Manoeuvre the ship and operate small ship power plants  | A                    |                      |                      |                      |
| Table A-II/5.2  | Contribute to berthing, anchoring and other mooring operations  | A                    | B                    | C                    | (S)                  |



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This Statement of Compliance is for the manufacturer offering the simulator for examination or mandatory simulator training and complies with the requirements of DNVGL-ST-0033 Maritime Simulator Systems.

Based on this statement of compliance, maritime training providers in possession of simulators that comply with the requirements of the standard can apply for a product certificate for "Maritime simulator". The simulator's function area and the simulator class according to the standard will be stated on the certificate.

